

Max300 Manual

Rev 1

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Overview

Based on JFT's Intellipixel Architecture, Max300 is a high end yet most cost effect camera system in the industry. Equipped with top performance CMOS image sensor, powerful CPU + FPGA and flexible I/O's, Max300 is suitable to handle the most demanding image capturing and real-time processing applications.

Typical Applications

- o Motion Capturing for Biomechanical Analysis and Animation
- Virtual Reality, Immersive Training and Simulation
- o Machine Vision and Automation
- Centroid Detection and Projectile Tracking that require the highest tracking accuracy and speed
- o Vehicle or Ship Mount
- High speed video and slow-motion Analysis
- o Sports and medical

Key Camera Specs

- o Basic network consists of 1-14 cameras with global timing and genlocking
- Multiple basic networks can be joined to form a larger capturing system with up to 224 cameras
- o 2048x1088 native resolution, 65536 x 34816 sub-pixel resolution
- o 10-320 FPS at full resolution
- \circ With 2:1 and 4:1 row skipping, support 600 FPS and 1200FPS with the same FOV
- Support both area and line scan mode
- o 20000 FPS with 16 scan rows

- $\circ~$ Support multi-camera interleaving with increased effective frame rate. N x 320 FPS at full resolution with N camera interleaving
- Support embedded in line gen-locking and SYNC offset among cameras. A camera can be configured as either SYNC master or SYNC slave
- o 1 to 256 markers. Real time marker detection, extraction and streaming
- 0.02 mRad object, marker or light tracking accuracy (at 36⁰ FOV)
- Marker information includes timing, centroid, size and intensity plus other customer specified info.
- o Software controllable gain, exposure, frame rate and threshold
- Uncompressed digital image can be streamed through Ethernet or HDMI with variable resolutions such as 1080P
- Single cable connection. Cameras are daisy chained by RJ45 cable with inline power. Cable length up to 250 feet
- Enhanced NIR performance. Working spectral response 380 ~ 980nm
- o NIR illuminator synchronized to shutter exposure for best motion capturing performance
- o True synchronous global shutter to eliminate image blurring and distortion
- Sub 0.01 lux light sensitivity (F1.4 lens without IR illuminator)
- During motion capturing, each camera can simultaneously record high speed video while streaming out marker information
- o 1GB internal DDR3 memory
- Optional SnapFilter allows the user to select the wavelength of interest by software controlled filter mover
- Sun light and background suppression allow the system to be used for both indoor and outdoor applications
- GigaBit Ethernet connection from Master Camera to host PC
- Trigger In and Trigger Out support for precise user controlled motion capturing
- Sync In and Sync Out ports can be used to join multiple basic camera networks for scalability
- Image sensor size : 2/3"
- Power Input : 15V-50V. Inrush current < 0.5A, operating current < 0.3A (at 15V)
- Operating Temperature Range: $-20^{\circ}C \sim 50^{\circ}C$
- Camera mount: Standard tripod mounts, two on the top, two on the bottom, 1/4 20 UNC
- Latency (event to processed output): < 1 frame time



System Connection

A Basic Network consists of 1-14 cameras. Camera 1 is also the master camera, which serves as the bridge between PC and all cameras.

Figure 1. Interconnecting Host PC, Master Camera and DS (Daisy Chain) Cameras



Both GigE and HS-BUS use standard RJ45 cross over cables. Please note that the power to all the DS cameras are provided in line through RJ45 Cables. If a router is used, the connection between PC to router and router to master camera will use standard RJ45 straight through cables. For basic network with less than 4 cameras, POE can supply power to master and DS camera, otherwise, an external power adaptor will have to be used.



Master Camera I/O Description:



- 1. GigaBit Ethernet Port with POE
- 2. USB Serial
- 3. USB 2.0 (Optional)
- 4. HDMI output
- 5. External Accessible DIP Switch to set the operation mode



- 6. HS-BUS for DS cameras 2-7
- 7. HS-BUS for DS cameras 9015
- 8. Trigger In and Sync In to control capturing start stop and for multi-network gen-locking
- 9. Trigger Out and Sync Out to control start stop of peripheral devices and for multi-network gen-locking
- 10. LED Indicator
- 11. Power input, 15VDC ~ 50VDC



DS Camera I/O Description:



- 1. USB Serial
- 2. USB 2.0 (Optional)
- 3. HDMI output
- 4. External Accessible DIP Switch to set the operation mode
- 5. HS-BUS for upstream camera connection
- 6. HS-BUS for downstream camera connection
- 7. LED Indicator



HS-BUS Connector Pinout (At Camera Side):

| Pin Number (RJ45) | Signal Name | Туре | Definition |
|----------------------|----------------|--------------|-------------------|
| 1 | TX_P | Output | HS-BUS TX+ |
| 2 | TX_N | Output | HS-BUS TX- |
| 3 | RX_P | Input | HS-BUS RX+ |
| 4 | POWER | Power In/Out | DC power, 15V-50V |
| 5 | POWER | Power In/Out | DC power, 15V-50V |
| 6 | RX_N | Input | HS-BUS RX- |
| 7 | GND | Ground | Ground |
| 8 | GND | Ground | Ground |

Status LED

| Number | Position | Name | Description |
|--------|------------------------|----------------|-----------------------------------|
| 1 | Тор | EVENT_EN | Event detect is enabled when lit. |
| 2 | 2 nd to the | FRM_CNT | This LED flashes at a frequency |
| | top | | that is frame rate divided by 64 |
| 3 | 3 rd to the | nBG_SUPRESSION | Lit for normal operation, dim |
| | top | | when background suppression is |
| | | | enabled |
| 4 | Bottom | EVENT_DET | Flash on when event(s) is |
| | | | detected |



Functions Supported by Software API

| Commands | Comments |
|--|---|
| Read Register and Memory of Master Camera | |
| Read Register and Memory of DS Camera | |
| Write Register and Memory of Master Camera | |
| Write Register and Memory of DS Camera | |
| Init | Initialize cameras in the network and achieve gen- locking |
| Read Version Number of Selected Camera(s) | |
| Set a Selected Camera to Stream Frame Data | |
| Set All or Selected Cameras to Stream Processed Data | |
| Clear Local Timers of Selected Cameras | |
| Enable Local Timers of Selected Cameras | The timer is used to time tag processed image data |
| Assign Cameras to be Active | Inactive Cameras do not Stream Data or Respond to Host Command |
| Check Camera Presence and Sync Status | |
| Get the Number of Cameras Connected | |
| Get Exposure Time of Selected Camera(s) | |
| Set Exposure Time of Selected Camera(s) | |
| Get Frame Rate of Selected Camera(s) | |
| Set Frame Rate of Selected Camera(s) | |
| Set Max Frame Rate of Selected Camera(s) | Set maximum frame rate at the current resolution |



| Get Gain of Selected Camera(s) | |
|---|---|
| Set Gain of Selected Camera(s) | |
| Get Threshold of Selected Camera(s) | |
| Set Threshold of Selected Camera(s) | |
| Set Threshold Type | E.g., white detection, black detection, delta detection |
| Set Spot Separation Get | Define the pixel separation to be considered as two spots |
| Set Minimum Spot Size | Define the minimum size of an object that will be detected |
| Get Filter Position of Selected Camera(s) | |
| Set Filter Position of Selected Camera(s) | |
| Enable External Trigger | Allows starting and stopping capturing and/or video recording with external trigger button |
| Start/Stop Triggering | Software controlled start and stop without external button |
| Disable External Trigger | |
| Enable Video Recording of Selected Camera(s) | Allow a given camera to record high speed video into internal memory storage |
| Start Video Recording of Selected Camera(s) | |
| Stop Video Recording of Selected Camera(s) | |
| Get the Size of Frame Storage | <i>In number of frames based on the current resolution setting. The frame storage is circular</i> |
| Set the Size of Frame Storage | |
| Get the Position of the Last Frame when Video | |



| Recording is Stopped | |
|--|--|
| Play Back Recorded Video | Through Ethernet, HDMI, HS-BUS |
| Play Back Selected Frame(s) | |
| Background Filtering | Eliminate unwanted background scenes and lights. |
| | Useful for outdoor operation and ultra-low signal |
| | detection |
| Image Inversion | |
| Image X and/or Y Flip | |
| Set Sensor Resolution | |
| Set Row Skipping | |
| Set Video Record X Subsampling | This does not change the sensor output. It only affects |
| | the recording format to increase the effective |
| | recording time |
| Cat Video Decend V Cuberranius | This does not all successful and successful the sub- offered |
| Set video Record Y Subsampling | This does not change the sensor output. It only affects |
| | the recording format to increase the effective |
| | recording time |
| Enable Image Processing with Subsampled Data | The default is to process every line and every pixel |
| | from sensor output |
| 2:1 Image Playback Scaling Enable | Only applies to Ethernet and HS-Bus video streaming. |
| | Used to accommodate PC's with lower screen |
| | resolution |
| Read Camera Internal Temperature | |
| Read Operating Voltages | For trouble shoot purpose |
| Reset Camera | |
| Set Internal Image Pattern Generation | For testing purpose |



| Set SYNC Offset to Allow Camera Interleaving | To increase the effective combined frame rate of a |
|---|---|
| | |
| Disable Gen-locking for Selected Camera(s) | Allows cameras in the network to operate at different |
| | frame rates and resolutions |
| Set Selected Camera(s) to Report Extracted Data | Report pixels that are extracted based on extraction |
| | algorithm |
| Set Selected Camera(s) to Report Spot Centroid | |





Middle Body Section:

